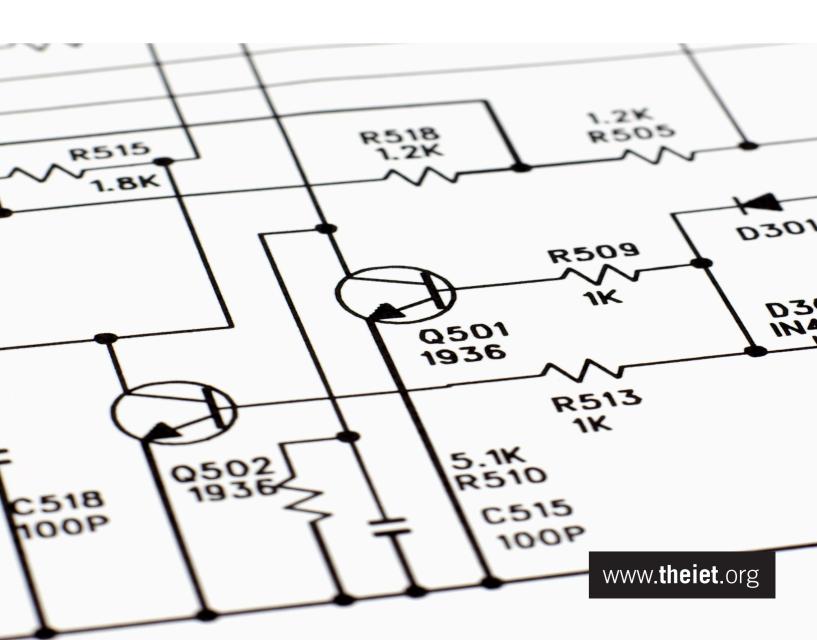


Units & Symbols for Electrical & Electronic Engineers



Preface

A booklet, Symbols and Abbreviations for use in Electrical and Electronic Engineering Courses, was published by the Institution of Electrical Engineers in 1968 and 1971. To take account of the many revisions and additions to British and International Standards since then, a new and fully revised edition was published in 1979, with reprints in 1980 and 1983.

In 1985, the editorial panel reconvened and undertook a total review and update of the Symbols and Abbreviations booklet, prior to it being re-issued under its new title in the professional brief series, in 1986. Further reviews of the contents were undertaken in 1991 and 1996. Any comments on the present content, or suggestions for additional material, will be welcomed. Please address comments to the Secretary of the Institution.

The booklet is for use by students and staff in colleges and universities, as a reference for authors of papers and books on electrical and electronic engineering and related subjects, and as a guide for draughtsmen and designers in industry.

Appendix A lists the standards which have been used in the preparation of this Guide.

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Introduction

In the expression I = 16 mA, I is the quantity symbol for the physical phenomenon of electric current, and 16 is its numerical value in terms of the decimal submultiple (10^{-3}) of a unit (ampere) of current; mA is the unit symbol for milliampere. Other symbols (such as j, exp, Cu) are used to indicate mathematical operations, chemical elements etc. Frequently occurring technical phrases are commonly rendered as abbreviations (such as e.m.f., p.d.). In circuit diagrams, graphical symbols identify network components and devices.

International letter symbolism is based on the Roman and Greek alphabets. There are fewer than 90 distinctive capital and small letters to represent some thousands of scientific and technical quantities, and extensive duplication is unavoidable. Priority is given here to electrical, electronic and manufacturing engineering, and quantities in associated fields are, where necessary, assigned alternative or second-choice symbols.

The units and symbols listed throughout this booklet conform to the recommendations of the International Electrotechnical Commission (IEC) and the British Standards Institution (BSI). Additionally, because of their common usage, in the Logic Symbols under Section 12 some distinctive-shape binary logic symbols have been used.

1. Abbreviations for Words & Phrases

Well known abbreviations, such as those listed below, are set in small roman (lower-case upright) letters, except for proper names, the unit system (SI), at the start of a sentence (e.g. A.C., not A.c.), and in titles and table headings where preferred:

Alternating current*	a.c	Phase†	ph.
Direct current*	d.c.	Potential difference	p.d.
Electromotive force	e.m.f.	Power factor	p.f.
Per unit	p.u.	Root mean square	r.m.s.

^{*}Adjective only, as in a.c. motor, d.c. circuit. †As in 3-ph. Supply

Ad hoc abbreviations (such as s.s.b. for single sideband) may be employed subject to an initial use in context of the full expression. Some acronyms (e.g. radar, laser) are used as nouns. The use of capital letters without full points for some abbreviations is common, particularly in the fields of logic, computers and microprocessors (see *Commonly used abbreviations in optical, logical and microprocessor curcuits* in Section 13).

2. Printing Conventions

For clarity, in scientific and technical literature, different types of object are printed in different typefaces. The normal printing conventions are as follows:

Object	Typeface	Examples
unit symbols	Roman	Hz, s, μm
scalar physical quantities	Italic	f, t
vector physical quantities*	Italic boldface or	· ·
the property of the second	Italic with arrow	!, E ₹, E
numbers and numerical constants	Roman	17, π, e
numerical variables	Italic	$x, x_{,,}, f(x)$
matrices	Italic boldface	$\stackrel{"}{A}$
standard mathematical functions	Roman	sin, log _e

Note: the four styles of typeface are (using the letter A as an example):

Roman (or 'upright'):	A	Roman boldface:	A
Italic (or 'sloping'):	A	Italic boldface:	\boldsymbol{A}

^{*}this typeface also applies to phasor physical quantities

Letter symbols, subscripts

Letter symbols should be used with consistency (e.g. only L for self-inductance, only P for power), but distinguishing subscripts can be attached (e.g. L_1 and L_2). Upper-case letters (e.g. V, I) are used for steady, mean and r.m.s values; lower-case letters for instantaneous values which vary with time (e.g. V, I). Maximum, minimum and average are indicated by subscripts (e.g. V_{max} , V_{min} , V).

3. Unit Symbols

Unit symbols are printed in upright roman characters and are used after numerical values (e.g. 10 A, but 'a few amperes'). They are the same in singular and plural, and are not followed by a full point except for normal punctuation, e.g. at the end of a sentence. A space is set between the number and its unit symbol (e.g. 230 V, not 230V). The decimal multiples and submultiples given below are prefixed, without a space, to the unit symbols (e.g. 6.6 kV). Compound decimal prefixes should not be used (e.g. pF, not $\mu\mu$ F).

10	yotta yotta	Y				10-3	milli	m
103	zetta zetta	Z				10-6	micro	μ
10		E	10 ²	hecto	h	10-9	nano	n
10		Р	10^{1}	deca	da	10 ⁻¹²	pico	р
10	tera	Т	10-1	deci	d	10 ⁻¹⁵	femto	f
10	⁹ gigi	G	10-2	centi	С	10 ⁻¹⁸	atto	а
10	6 mega	M				10 ⁻²¹	zepto	Z
10	³ kilo	k				10 ⁻²⁴	yocto	У

Powers in steps of 3 are preferred, but some others have common usage (e.g. centimetre cm, decibel dB).

Compound symbols

In a compound unit symbol, multiplication is denoted by either a dot or a space (e.g. $N \bullet m$, N m). The last form may also be written without a space, provided that special care is taken when the symbol for one of the units is the same as the symbol for a prefix, e.g. mN means millinewton, not metre newton. Unit division may be indicated by a solidus (e.g. V/m). Not more than one solidus should appear in a combination (e.g. $5 m/s^2$, not 5 m/s/s). In some cases parentheses or negative powers may be used for clarity (e.g. 1/s or s^{-1} ; J/(m s K) or $J m^{-1} s^{-1} K^{-1}$).

4. Numerical Values

Numbers should generally be printed in roman (upright) type. To facilitate the reading of numbers with many digits, these may be separated into suitable groups, preferably of three digits, counting from the decimal sign towards the left and the right; the groups should be separated by a small space, and never by a comma or a point, nor by any other means.

The decimal sign

The IEC and the BSI indicate that a comma on the line is the preferred decimal sign. In most British Standards, most UK literature, and all USA literature it is the practice to use a dot on the line as the decimal marker. In order to avoid confusion the IET adopts the convention of English literature publications and uses a dot on the line as the decimal marker.

Multiplication of numbers

In the UK the preferred sign for the multiplication of numbers is a cross (X); if a dot is used as the decimal sign, the cross must be used. (A dot half-high may be used as the multiplication sign for numbers, but in this case a comma should be used as the decimal sign.)

5. The International System of Units

The International System of Units (SI) establishes three kinds of units: base, supplementary, and derived, discussed in the following sub-sections under Section 5. In addition, various other units, listed under the sub-heading Non-SI Units, are recognised for continued use alongside SI units. Many obsolescent non-SI units are listed in Section 11, where conversion factors are given.

SI base units and supplementary units

There are seven base units and two supplementary units, as shown below:

Base quantity	Name of SI base unit	Unit symbol
length mass time electric current thermodynamic temperature amount of substance luminous intensity	metre kilogram second ampere kelvin mole candela	m kg s A K mol cd
plane angle solid angle	radian steradian	rad sr

The definitions of these units are as follows:

- metre (m): the metre is the length of the path travelled in vacuum by light during (1/299 792 458) second.
- **kilogram** (kg): the mass of the international prototype of the kilogram.
- **second** (s): the duration of 9 192 631 770 periods of the radiation corresponding to the transition between the two hyperfine levels of the ground state of the caesium¹³³ atom.
- **ampere** (A): that constant current which, if maintained in two straight parallel conductors of infinite length, of negligible circular cross-section, and placed 1 metre apart in vacuum, would produce between these conductors a force equal to 2 x 10⁻⁷ newton per metre of length.
- **kelvin** (K): the unit of thermodynamic temperature is the fraction 1/273.16 of the thermodynamic temperature of the triple point of water (but see footnote*).
- **candela** (cd): the luminous intensity, in a given direction, of a source which emits monochromatic radiation with a frequency 540×10^{12} hertz and whose energy intensity in that direction is (1/683) watt per steradian.
- **mole** (mol): the amount of substance of a system which contains as many elementary entities as there are atoms in 0.012 kilogram of carbon¹². When the mole is used, the elementary entities must be specified and may be atoms, molecules, ions, electrons, other particles, or specified groups of such particles.
- radian (rad): the plane angle between two radii of a circle which cut off on the circumference an arc equal in length to the radius.
- **steradian** (sr): the solid angle which, having its apex at the centre of a sphere, cuts off an area of the surface of the sphere equal to that of a square with sides of length equal to the radius of the sphere.

The supplementary units 'radian' and 'steradian' are to be regarded as dimensionless derived units which may be used or omitted in the expressions for derived units.

^{*} In addition to the thermodynamic temperature (symbol T), expressed in kelvins, use is also made of Celsius temperature (symbol t) defined by the equation $t = T-T_0$ where $T_0 = 273.15$ K by definition. The unit 'degree Celsius' is equal to the unit 'kelvin', but 'degree Celsius' is a special name in place of 'kelvin' for expressing Celsius temperature. A temperature interval or a Celsius temperature difference can be expressed in degrees Celsius as well as kelvins, but kelvin is to be preferred.

SI derived units

The units of all physical quantities are derived from the base and supplementary SI units, and certain of them have been named. These, together with some common compound units, are given here:

Quantity	Unit Name	Unit Symbol	Expression in terms of SI base unit
force	newton	N	m kg s ⁻²
energy	joule	J	m ² kg s ⁻²
power	watt	W	m ² kg s ⁻³
pressure, stress	pascal	Pa	m ⁻¹ kg s ⁻²
electric potential	volt	V	m ² kg s ⁻³ A ⁻¹
electric charge	coulomb	C	s A
electric flux	coulomb	C	s A
magentic flux	weber	Wb	m ² kg s ⁻² A ⁻¹
magnetic flux density	tesla	T	kg s ⁻² A ⁻¹
electric resistance	ohm	Ω	m ² kg s ⁻³ A ⁻²
electric conductance	siemens	S	m ⁻² kg ⁻¹ s ³ A ²
capacitance	farad	F	m ⁻² kg ⁻¹ s ⁴ A ²
inductance	henry	Н	m ² kg s ⁻² A ⁻²
Celsius temperature*	degree Celsius	oC	K
frequency	hertz	Hz	S^{-1}
luminous flux	lumen	Im	cd sr
activity (of a radionuclide)	becquerel	Bq	S^{-1}
absorbed dose	grey	Gy = J/Kg	$\mathrm{m}^2\mathrm{s}^{-2}$
dose equivalent	sievert	Sv = J/Kg	$m^2 s^{-2}$
mass density	kilogram per cubic metre	kg/m³	m ⁻³ kg
moment of force	newton metre	N m	m ² kg s ⁻²
torque	mewton metre	N m	m ² kg s ⁻²
electric field strength	volt per metre	V/m	m kg s ⁻³ A ⁻¹
electrical displacement	coulomb per square metre	C/m ²	m ⁻² s A
magnetic field strength	ampere per metre	V/m	m ⁻¹ A
thermal conductivity	watt per metre kelvin	W m ⁻¹ K ⁻¹	m kg s ⁻³ K ⁻¹
luminance	candala per square metre	cd/m ²	m ⁻² cd

^{*}See footnote to previous sub-section - SI base units and supplementary units

Non-SI units

Some commonly used units not within the SI range are:

angle degree (1° = $\pi/180$ rad); minute (1' = ($\frac{1}{60}$)°) second (1" = ($\frac{1}{60}$)'); revolution (1 r = 2π rad)

energy calorie (cal); electronvolt (eV); watt-hour (W h)

length ångström (Å)

mass ton (ton); tonne (= metric ton) (t)

unified atomic mass unit (u)

pressure, stress atmosphere (atm); bar (bar); torr (Torr)

rotational frequency revolution per minute (r/min)*, revolution per second (r/s)*

time minute (min); hour (h); day (d); year (a)

volume litre (L, I or litre)

^{*}These are widely used for rotational frequency in specifications of rotating machinery.

6. Quantity Symbols for Mechanics, Thermodynamics, Illumination

As noted in Section 2, an italic typeface is used for quantity symbols.

Quantity	Symbol	SI Unit
acceleration, angular	α	rad/s ²
acceleration, linear	a	m/s ²
acoustic pressure	P	Pa
angle, plane	α, β, γ	rad
angle, solid	Ω	sr
angular momentum	L	kg m ² s ⁻¹
area, surface area	A, S	m^2
bulk compressibility	K	m²/N
coefficient of heat transfer	α	W m ⁻² K ⁻¹
density	ρ	kg/m ³
efficiency	7	-
energy	E	J
energy, kinetic	E.	J
energy, potential	E E	J
energy, volume density	$E_k \\ E_p \\ W$	J/m ³
enthalpy	H(=U=pV)	J
entropy	S	J/K
force	\overline{F}	N
frequency	f	Hz
frequency, angular	ω	rad/s
friction, coefficient	μ	-
friction, force coefficient	F	N s/m
friction, torque coefficient	F	N m s/rad
Gibbs function	G (=U+pV-TS)	J
heat, quantity of heat	Q	J
heat, heat capacity	\hat{C}	J/K
heat, specific heat capacity	c	J kg ⁻¹ K ⁻¹
heat, flow rate	$arphi_{th}$	W
heat, density of heat flow rate	q	W/m ²
Helmholtz free energy	A, F(A=U-TS)	J
illumunance	E	Lx
internal energy	U	J
isentropic exponent	$V \left(- \frac{V}{2} \left(\frac{\partial p}{\partial x} \right) \right)$	-
	$K \left(= -\frac{V}{p} \left(\frac{\partial p}{\partial V} \right)_{S} \right)$	
kinematic viscosity	v	m ² /s
length	1	m
luminance	L	cd/m ²
luminous flux	φ	lm
luminous intensity	1	cd
mass	m	kg
mass flow rate	$q_{\rm m}$	kg/s
mechanical impedance	Z _m E	N s/m
moduli, modulus of elasticity (Young)		Pa
moduli, longitudinal modulus of elasticity	Е	N/m ²
moduli, sheer modulus, modulus of rigidity	G	N/m ²
moduli, bulk modulus, modulus of compression	K	N/m ²
moment of force	M	Nm
moment of inertia	J	kg m ²

6. Quantity Symbols for Mechanics, Thermodynamics, Illumination (continued)

Quantity	Symbol	SI Unit
momentum	p	kg m/s
Poisson ratio	μ	-
pressure, stress	p	Pa
radius of gyration	k	m
ratio of specific heat capacities	$Y = \frac{c_p}{c_v}$	-
second axial moment of force	l _a	m^4
second polar moment of area	1.	m^4
specific heat capacity, constant pressure	l p c p	-
specific heat capacity, constant volume	c_{v}^{p}	-
specific heat capacity, staturation	c _{sat}	-
strain, linear	arepsilon	-
strain, sheer	Y	-
strain, volume strain, bulk strain	Θ	
surface tension	Y	N/m
temperature, thermodynamic temperature	Т, 🕖	K
temperature, Celsius temperature	t,	°C
temperature interval	_	K
thermal, conductivity	λ , k	w m ⁻¹ K ⁻¹
thermal, resistance	R _{th}	K/W
time	t	S
time constant	τ	S
torque	T	N m
velocity, angular	ω	rad/s
velocity, linear	V	m/s
viscosity	η	Pa s
viscosity, kimematic		m²/s
volume	V	m ³
volume, specific	V	m³/kg
volume, flow rate	g_{v}	m³/s
weight	G	N
work	W	j

7. Quantity Symbols for Electrotechnics

Quantity	Symbol	SI Unit	
admittance	Y	S	
attenuation	A	Np† dB†	
attenuation coefficient		m-1	
bandwidth	α	Hz	
	В	F	
capacitance	C		
charge	Q	C	
charge density, surface	σ	C/m ²	
charge density, volume	ρ	C/m ³	
conductance	G	S	
conductance, mutual	$g_{\rm m}$	S	
conductivity	<i>Υ</i> , σ	S/m	
control angle, rectifier	α	rad	
control angle, inverter	β	rad	
coupling factor	k	-	
current	I	A	
current density, area	J	A/m ²	
current density, linear	A	A/m	
current linkage	Θ	A	
damping coefficient	δ	s ⁻¹ (or Np/s)	
decrement, logarithmic	λ	- -	
dipole moment, electric		C m	
dipole moment, electric	p j	Wb m	
dissipation factor		-	
distortion factor	d d	-	
		- F/m	
electric constant	$rac{arepsilon_o}{ m E}$		
electric field, strength		V/m	
electric field, level	$\stackrel{ ext{L}_{ ext{e}}}{arphi}$	Np††	
electric flux		C	
electric flux density	D	C/m ²	
electric polarisation	P	C/m ²	
electric susceptibility	χ , χ_{ε}		
electromotive force	E	V	
energy	E, W_e	J	
energy, Fermi	8	J‡	
feedback factor	$oldsymbol{eta}$	-	
frequency	f	Hz	
frequency, angular	ω	rad/s	
frequency, deviation	Δf	Hz	
frequency, complex angular	p	S ⁻¹	
gain	G	-	
group velocity	c _g , v _g	m/s	
group delay	t g g	S	
Hall coefficient	$\overset{ ext{t}}{\overset{ ext{s}}{\mathcal{R}}_{ ext{h}}}, \overset{ ext{d}_{ ext{h}}}{\mathcal{Z}}$	m³/C	
impedance	Z.	Ω	
impedance, characteristic	Z_{\circ}	Ω	
impedance, surge	7	Ω	
inductance, self	Z_{\circ}	H	
	L	П Н	
inductance, mutual	L_{jk} , M		
leakage factor	σ	-	

[†] Not a SI unit but in common use—also see section 11 sub section **Special remark on Logarithmic quantities and units**

^{††} Not a SI unit but in common use

[‡] More usually expressed in eV

7. Quantity Symbols for Electrotechnics (continued)

Quantity	Symbol	SI Unit
loss angle	δ	rad
magnetic constant	$\mu_{\rm o}$	H/m
magnetic field strength	Н	A/m
magnetic flux	Φ	Wb
magnetic flux density	В	Т
magnetic flux linkage	Ψ	Wb
magnetic (area) moment	m	A m ²
magnetic polarisation	$B_{i}^{}J$	Т
magnetic susceptibility	χ, κ	-
magnetic vector potential	A	Wb/m
magnetisation	$H_{i}M$	A/m
magnetomotive force	F, f_{m}	A
mobility	μ	$m^2 V^{-1} s^{-1}$
modulation factor (a.m.)	m	-
modulation factor (f.m.)	δ	rad
noise factor	F, F _n	-
noise power	P n	W
noise temperature	P _n T _n	K
number density of particles	n n	m ⁻³
number of phases	m	- -
number of pole pairs, pulses	p	_
number of turns	N N	_
period	T	S
permeability, absolute	μ	H/m
permeability, relative		_
permeance	$oldsymbol{\mu_{_{\mathrm{r}}}}{\Lambda}$	H, Wb/A
permittivity, absolute	ε	F/m
permittivity, relative		_
phase, angle	\mathcal{E}_{r} Φ	rad
phase, delay		rad
phase, deviation	$\overset{t_{o}}{\Delta \Phi}$	rad
phase change	В	rad
phase-change coefficient		rad/m
phase velocity	β	m/s
polarisation, electric	c_{Φ}, v_{Φ}	C/m ²
polarisation, electric		T
potential	B _i , J V	V
potential potential difference		V
·	U, V	W
power, active	P	V A
power, reactive	S	
power, reactive power factor	$Q \lambda$	var†
•		-
power factor, sinusoidal	cos Φ	- Not dD+
power-level difference	-	Np†, dB†
Poynting vector	S	W/m²
propagation coefficient	γ	m ⁻¹
Q (quality) factor	Q	-
radiant energy	Q, W	J
radiation resistance	R_{r}	Ω

[†] Not a SI unit but in common use

7. Quantity Symbols for Electrotechnics (continued)

Quantity	Symbol	SI Unit	
rating	S	V A, W	
reactance	X	Ω	
reflection coefficient	r, p	-	
refractive index	n	-	
regulation	ε	p.u.†	
reluctance	R, R_m	H ⁻¹ , A/Wb	
resistance	R	Ω	
resistance-temperature coefficient	α	K-1	
resistivity	ρ	Ωm	
signal	S	-	
slip	S	-	
standing-wave radio	S	-	
susceptance	В	S	
susceptibility, electric	χ , χ_{ϵ}	-	
susceptibility, magnetic	χ, κ	-	
transconductance	$g_{\rm m}$	A/V, S	
transfer function	H	-	
transmission factor	τ	-	
turn-on, turn-off time	t_{on}, t_{off}	S	
voltage	U, V	V	
wavelength	λ	m	
work function	Φ	J ‡	

[†] Not a SI unit but in common use

[‡] More usually expressed in eV

8. Subscripts and other uses of Letters and Numbers

It is recommended as a guiding principle for the printing of subscripts that, when these are symbols for physical quantities, they should be printed in italic type. Numbers as subscripts should be printed in roman type; mathematical variables (e.g. running subscripts) should be printed in italic type. All other subscripts should be printed in roman type.

Some commonly used abbreviations, often occurring as subscripts, are as follows:

General

	T		
a	absolute	exp	experimental
u	acoustic	CAP	CAPCITITETICAL
	active	f	field
	additional	'	filament, heater
	1		final
	alternating		
	ambient		forward
	anode		frequency
	anti-resonance	fl	floating
	axial		
amb	ambient	g	airgap
as	asynchronous		gate
av	average		grid
			group
b	backward		
	base	h	hysteresis
br	breakdown		height, depth
	1		hybrid
С	calculated		, ~
	carrier	i	ideal
	case	·	image
	coercive		induced
	collector		initial
	correction		l l
	1		input
	critical		instantaneous
-1-	cut-off		intermediate
ch	chemical		internal
ср	composite		intrinsic
cr	critical	im	image
	l	in .	insertion
d	d-axis	ind	indirect
	damped		
	delay	j	junction
	deviation		
	diameter	k	cathode
	difference		knee
	diffuse		iterative
	direct		short circuit
	dissipation	K	transformation ratio
	distortion		
	dynamic	I	leakage
dem	demodulation		limiting
			line
е	effective		local
	electric		longitudinal
	emitter	L	load
	equivalent		large signal
	error		
	external		
	1		

8. Subscripts and other uses of Letters and Numbers (continued)

m magnetic magnetising maximum measured mechanical mutual peak value median min minimum modulation n natural noise nominal n output spherical characteristic in vacuo opt opt opt opt of ov overload now med or overload now max maximum peak value med med median minimum peak value nose nominal nose nominal nose noptical standardised static stator stator stator stator stator starage synchronous starage synchronous starage synchronous starage short-circuit now maximum peak value ref reference reference reference rotational rotor reference rotational rotor research rotational rotor research rotational rotor research static reference rotational rotor reference reverse transfer rotational rotor reference reverse transfer rotational rotor reference resulting reverse reverse transfer rotational rotor reference rotational rotor reference rotational rotor reference reverse transfer rotational rotor reference reverse transfer rotational rotor reference stational rotor reference reverse transfer rotational rotor reference reverse transfer rotational rotor reference rotational rotor reference stational rotor reference rotational rotor reference reverse transfer rotational rotor reference reference reverse transfer rotational rotor reference reverse transfer rotational rotor reference re	
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mechanical mutual peak value max med min min mod mod natural noise nominal output spherical characteristic in vacuo ope opt opt or	
mutual peak value max med min min mod nod notural noise nominal notuput spherical characteristic in vacuo open circuit or	
max med maximum median median min minimum mod modulation segment series signal noise nominal standardised static spherical characteristic in vacuo opt opt opt original sat sat saturation root mean square value secondary segment series signal spherical signal standardised static static stator st	
max medmaximum medianrmsroot mean square valuemin modminimum modulationssecondary segment series signal spherical spherical standardised staticnnatural noise nominalsignal spherical standardised static stator steady issue storage synchronous synchronous saturation	
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n natural noise nominal signal spherical standardised static output spherical characteristic in vacuo open circuit opt opt optical or original sat sat saturation	
noise nominal standardised static stator spherical characteristic in vacuo oc open circuit opt optical or original standardised static stator stator steady issue storage synchronous sat saturation	
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output spherical characteristic in vacuo open circuit opt optical or original stator steady issue storage synchronous saturation	
spherical characteristic in vacuo open circuit opt opt or or spherical characteristic in vacuo steady issue storage synchronous sat sat saturation	
ocopen circuitstorageoptopticalsynchronousororiginalsatsaturation	
optopticalsynchronousorsatsaturation	
or original sat saturation	
sim simultaneous	
p parallel, shunt sinusodial	
parasitic stg storage	
pole, or pairs of poles successive	
primary	
psophometric t tangential	
pulse tangential total	
pd pull down transient	
ph phase transmission	
pk peak transverse	
pt th thermal	
pull up theoretical	
p-p peak-to-peak total	
q-axis usual	
quadrature useful	
quiescent	
turn off v luminous	
vartying	
radical vacuum	ſ
radiation	ſ
rated	
real wdg winding	
relative	ſ
reflection x reactive	ſ
remanent crosstalk	
residual	

8. Subscripts and other uses of Letters and Numbers (continued)

0	characteristic free space no load zero frequency	2	negative sequence output port 2 second harmonic secondary
1	full load fundamental input port 1 positive sequence primary	3 , p ⊥, n 0, s ∞	tertiary parallel perpendicular spherical at infinity

Semiconductors

To the incremental hybrid (h), admittance (y) and impedance (z) parameters, double subscripts are applied in the order (1) function, (2) common electrode:

- (1) i or 11 input; o or 22 output; f or 21 forward transfer; r or 12 reverse transfer.
- (2) b base; c collector; d drain; e emitter; g gate; s source (e.g. h_{oe}, y_{12h}).

The upper-case variant of the subscript is used for static (d.c.) or large-signal values (e.g. h_{FE} , h_{21F}).

The real and imaginary parts of a device impedance are shown, respectively, by Re and j Im (e.g. $h_{ie} = \text{Re}(h_{ie}) + \text{j Im}(h_{ie})$).

Upper-case letters are used for the representation of electrical parameters of external circuits and all inductances and capacitances. Except for L and C, lower-case letters are used for electrical parameters inherent in the device (e.g. $r_{\rm e}$). In equivalent circuits using 3-terminal devices, a third letter may be used to indicate the condition at the third terminal (e.g. $V_{\rm CBO}$ where $I_{\rm E}=0$), while the first subscript indicates one terminal of the device and the second subscript the reference terminal or circuit node.

9. Mathematical Symbols

Term	Symbol
$\sqrt{-1}$ ratio of circumference to diameter of circle base of natural logarithms exponential function (to the base e) of x logarithm to the base a of x natural logarithm of x common logarithm of x binary logarithm of x	j $\pi(\approx 3.141\ 592\ 654)$ e ($\approx 2.718\ 281\ 828)$ e ^x , exp x $\log_a x$ $\ln x \ (\equiv \log_c x)$ $\lg x \ (\equiv \log_1 x)$ $\lg x \ (\equiv \log_2 x)$
circular functions of <i>x</i> inverse circular functions of <i>x</i> hyperbolic functions of <i>x</i> inverse hyperbolic functions of <i>x</i>	$\sin x$, $\cos x$, $\tan x$ $\arcsin x$, $\arccos x$, $\arctan x$ $\sinh x$, $\cosh x$, $\tanh x$ $\operatorname{arsinh} x$, $\operatorname{arcosh} x$, $\operatorname{artanh} x$
sum product function f value of the function f at x limit to which $f(x)$ tends as x approaches a finite increment of x variation of x total differential of f operators $\frac{\partial}{\partial x} \frac{d}{dx}$ differential coefficient of order $f(x)$ partial differential coefficient of order $f(x, y,)$ with respect to x , when y , are held constant indefinite integral of $f(x)$ from	$\sum_{\Pi} f$ $f(x)$ $\lim_{x \to a} f(x)$ Δx ∂f df D_x, D $\frac{dnf}{dx^n}, f^{(n)}(x)$ $\frac{\partial f}{\partial x}(x, y,), \left(\frac{\partial f}{\partial x}\right)_y,$ $\int f(x) dx$ $\int_a^b f(x) dx$
x = a to $x = bconvolution product of f and x$	f*g
inverse of the square matrix A transpose matrix of A complex conjugate matrix of A determinant of the square matrix A	$\begin{pmatrix} A_{11} & \dots & A_{1n} \\ \vdots & \vdots & \vdots \\ A_{m1} & \dots & A_{mn} \end{pmatrix}$ A^{-1} A^{T}, \tilde{A} A^{*} $det A, \begin{vmatrix} A_{n} & \dots & A_{1n} \\ \vdots & \vdots & \vdots \\ A_{n} & \dots & A_{nn} \end{vmatrix}$

9. Mathematical Symbols (continued)

Term	Symbol
vector A	\overrightarrow{A} , (A also used)
magnitude of the vector A	A, $ A $
scalar product of A and B	A • B
vector product of A and B	$A \times B$
del operator	∇
gradient of ø	∇ ø, grad ø
divergence of A	$\nabla \cdot A$, div A
curl of A	$\nabla x A$, curl A
Laplacian	$\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$
D'Alembertian	$\Box = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} - \frac{1}{c^2} \cdot \frac{\partial^2}{\partial t^2}$

10. Physical Constants

Quantity	Symbol	Numerical Value	Unit
acceleration of free fall (standard)	a	9.806 65*	m/s^2
atmospheric pressure (standard)	g _n	1.013 25 x 10 ⁵ *	Pa
atomic mass constant (unified)	p _o	1.660 540 x 10 ⁻²⁷	kg
Avogadro constant	${f m}_{ m u} \ {f N}_{ m A}$	6.022 137 x 10 ²³	mol ⁻¹
Bohr magneton		9.274 015 x 10 ⁻²⁴	J/T
Boltzmann constant	$\mu_{_{\mathrm{B}}}$	1.380 658 x 10 ⁻²³	J/K
elementary (proton) charge	e	1.602 177 x 10 ⁻¹⁹	C
electron: charge	-e	-1.602 177 x 10 ⁻¹⁹	C
electron: rest mass		9.109 390 x 10 ⁻³¹	kg
electron: charge/mass ratio	m _e e/m _e	1.758 820 x 10 ¹¹	C/kg
Faraday constant	F	9.648 531 x 10 ⁴	C/mol
free space: electric constant		8.854 188 x 10 ⁻¹²	F/m
free space: intrinsic impedance	$\mathcal{E}_{_{\mathrm{o}}}^{}$	376.730 3	Ω
free space: magnetic constant		4π x 10 ⁻⁷	H/m
free space: speed of e.m. waves	$\mu_{\rm o}$	2.997 924 58 x 10 ⁸ *	m/s
gravitational constant	G	6.672 59 x 10 ⁻¹¹	$N m^2 kg^{-2}$
ideal molar gas constant	R	8.314 510	J mol ⁻¹ K ⁻¹
neutron rest mass		1.674 929 x 10 ⁻²⁷	
Planck constant	m _n	6.626 076 x 10 ⁻³⁴	kg
normalised (h/2π)	h	1.054 573 x 10 ⁻³⁴	Js
	ħ	1.602 177 x 10 ⁻¹⁹	J s C
proton: charge	+e	1.672 623 x 10 ⁻²⁷	
proton: rest mass	m_{p} e/m_{p}		kg
proton: charge/mass ratio	e/m_p	9.578 831 x 10 ⁷	C/kg
radiation constants	$c_{_{1}}$	3.741 775 x 10 ⁻¹⁶	W m ²
Classes Dalla and a second and	c_2	1.438 769 x 10 ⁻²	m K
Stefan-Boltzmann constant	σ	5.670 51 x 10 ⁻⁸	W m ⁻² K ⁻⁴
unified atomic mass unit (is one twelfth o		1.660 540 x 10 ⁻²⁷	kg
the mass of the atom of the nuclide 12C)		004.45	
velocity of sound in air (s.t.p.)	С	331.45	m/s

^{*} exact values

Values of physical constants (apart from speed of sound) derived from CODATA Bulletin No. 63, Nov. 1986.

11. Conversion Factors

Exact values are shown with an asterisk *. Some of these units may no longer have a legal validity.

Length

0		
1 Å	100.0*	pm
1 mil	25.4*	μm
1 in	25.4*	mm
1 ft	0.304 8*	m
1 yd	0.914 4*	m
1 mile	1.609 344*	km
1 nautical mile	1.852*	km
1 astronomical unit	0.149 597 87*	Tm
1 light year	9.460 3	Pm

Area, Volume

1 in^2	645.16*	mm²
1 ft ²	0.092 903 04*	m^2
1 yd²	0.836 127	m ²
1 ha	10 000.0*	m ²
1 in ³	16 387.064*	mm ³
1 litre	1.0*	dm ³
1 UK fluid ounce	28.41 x 10 ⁻⁶	m^3
1 UK gal	4.546 09	L
1 US gal	3.785 41	L
1 ft ³	0.028 316 8	m^3
1 yd ³	0.764 555	m^3
1 mile ² (640 acres)	2.589 98	km ²
1 are	100.0*	m^2
1 acre (4840 yd²)	4 046.855	m ²

Mass, Density

1 oz (adp)	28.35	g
1 oz (troy)	31.10	g
1 lb	0.453 592.37*	kg
1 tonne	1 000.0*	kg
1 (UK) ton	1 016.05	kg
1 lb/ft ³	16.018 5	kg/m ³
1 lb/in ³	27.68	Mg/m ³
1 cwt (UK)	50.802 3	kg
1 carat	0.2*	g

Velocity

1 ft/s	0.304 8*	m/s
1 mile/h	0.447 04*	m/s
1 knot	0.514 4	m/s

Force, Pressure, Torque

1 ozf	278.0	mN
1 lbf	4.448 22	N
1 kgf	9.806 65*	N
1 Torr	133.322	Pa
1 mm Hg	133.322	Pa
1 in H ₂ O	249.09	Pa
1 m H ₂ 0	9.806 65*	kPa
1 bar ²	100.0*	kPa
1 lbf/in ²	6.894 76	kPa
1 ft lbf	1.355 82	N m
1 dyne	10.0*	μN
1 standard atmosphere	0.101 325*	MPa

Energy, Power

1 -1/	0.100.010.0	- 1
1 eV	0.160 218 2	aJ
1 cal (international table)	4.186 8*	J
1 Cal (= 1 kcal thermochemical)†	4.184*	kJ
1 ft lbf	1.355 82	J
1 m kgf	9.806 65*	J
1 Btu	1.055 06	kJ
1 therm	105.506	MJ
1 kW h	3.6*	Mj
1 ft lbf/s	1.355 82	W
1 m kgf/s	9.806 65*	W
1 Btu/h	0.293 071	W
1 hp (UK)	0.745 7	kW
1 erg/s	0.1*	μW

[†] Widely used for energy content of food. (There are different 'calories', of marginally different sizes; also note that the 'big calorie', used in newspapers etc., is 1000 times the corresponding 'small calorie'.)

Nucleonics, Radiation

Curie	1 Ci	3.70 x 10 ¹⁰ *	Bq
rad	1 rd	0.01*	Gy
Röntgen	1 R	2.58 x 10 ⁻⁴ *	C/kg
barn	1 barn (or 1 b)	10 ⁻²⁸ *	m^2
foot-candle	1 ft cd	10.76	lx

Special remark on logarithmic quantities and units

The expression for the time dependence of a damped harmonic oscillation can be written either in real notation or as the real part of a complex notation

$$F(t) = A e^{-\partial t} \cos(\omega t) = Re(A e^{-(\partial + j\omega)t})$$

This simple relation involving ∂ and ω can be obtained only when e (base of natural logarithms) is used as the base of the exponential function. The coherent SI unit for the damping coefficient ∂ and the angular frequency ω is second to the power minus one, i.e. 1/s. Using the special names neper, Np, and radian, rad, for the units of ∂ t and ω t respectively, the units for ∂ and ω become neper per second, Np/s, and radian per second, rad/s, respectively. Neper and radian are special names for the 'dimensionless' unit one, 1. The neper is used as a unit for logarithmic quantities; the radian is used as a unit for plane angles and for the phase of circular functions.

Corresponding variation in space is treated in the same manner

$$F(x) = A e^{-\alpha x} \cos(\beta x) = Re(A e^{-\gamma x}), \gamma = \alpha + j\beta$$

where the unit for α is neper per metre, Np/m, and the unit for β is radian per metre, rad/m.

In ISO 31, the level of a field quantity is therefore defined as the natural logarithm of a ratio of two amplitudes, $L_F = \ln(F/F_0)$, and is hence a quantity of dimension one. The unit neper (= the number 1) is the level of a field quantity when $F/F_0 = e$.

Since power is often proportional to the square of an amplitude, a factor 1/2 is introduced in the definition of the level of a power quantity $L_p = (1/2) \ln(P/P_0)$ in order to make the level of the power quantity under these circumstances equal to the level of the field quantity.

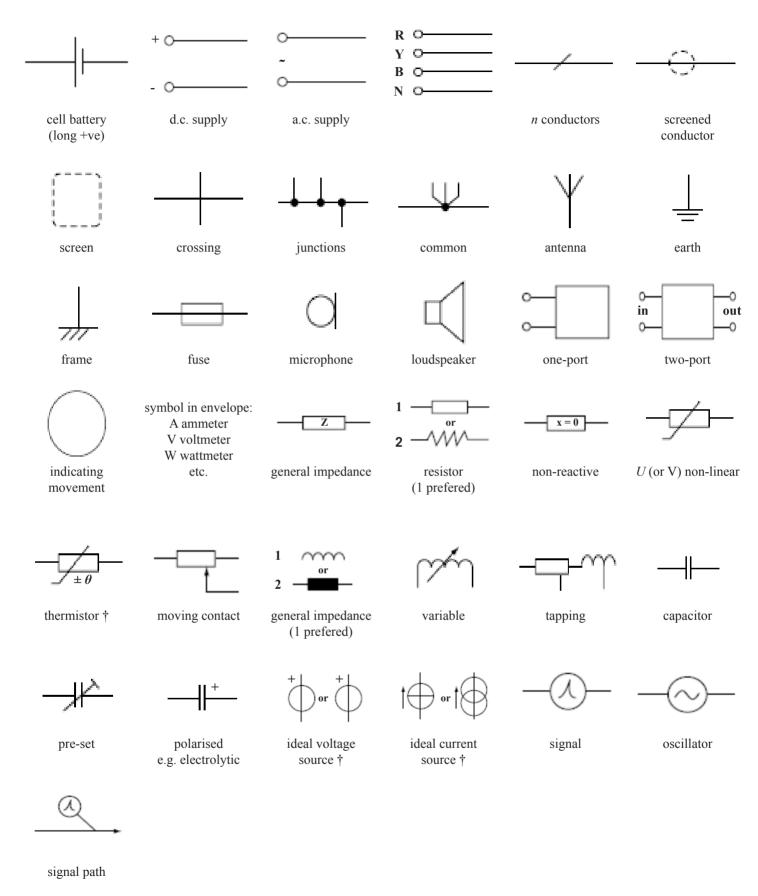
In practice the non-coherent unit degree, ...°, (1° = $\pi/180$ rad) is often used for angles and the non-coherent unit bel, B, [1 B = (1/2) \log_e^{10} Np ≈ 1.151 293 Np] is based on common logarithms (base 10) for logarithmic quantities. Instead of the bel, its submultiple the decibel, dB, is commonly used.

Some numerical conversion factors are:

power level	1 dB	0.05 log _e 10 Np (=0.115 129 Np)
	1 Np	20 log₁₀ e dB (≈8.686 dB
frequency	1 octave	log ₁₀ 2 decade (≈0.301 decade)
	1 decade	\log_2^{10} 10 octave (\approx 3.321 octave)

12. Graphical Symbols

Connections and network elements



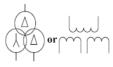
† Not in BS but in common use

Power plant

Transformers:



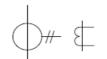
2-wdg



3-wdg



auto



current or pulse

if desired, core shown by single line annotated to indicate material

Machines:



descriptive symbols in envelope: G (generator), M (motor), G d.c., M

S (synchronous), GS, MS



linear M



stepping M



wdgs



M starter







circuit-breaker



isolator



gap



bridge rectifier



converter



etc.

Electronic devices

Amplifiers:



general



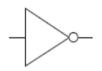
operational



parametric



integrating

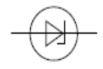


inverting

Diodes:



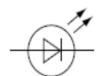
general



breakdown diode, Esaki diode



photo-diode



light emitting diode



tunnel diode

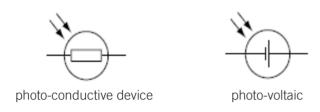


varactor

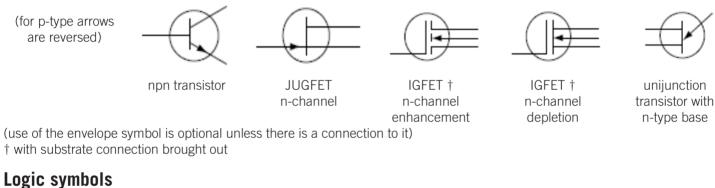
Thyristors:

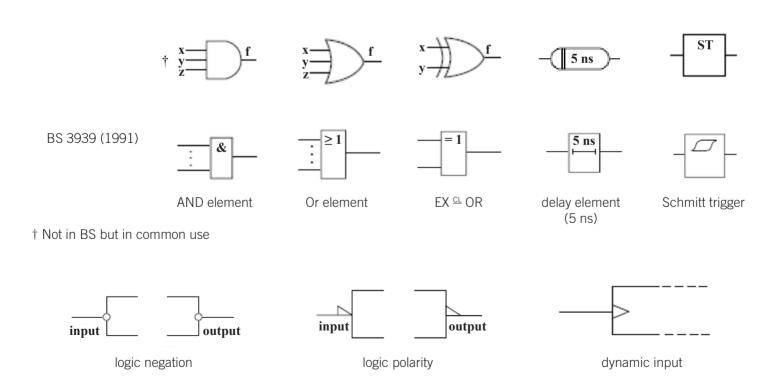


Cells:

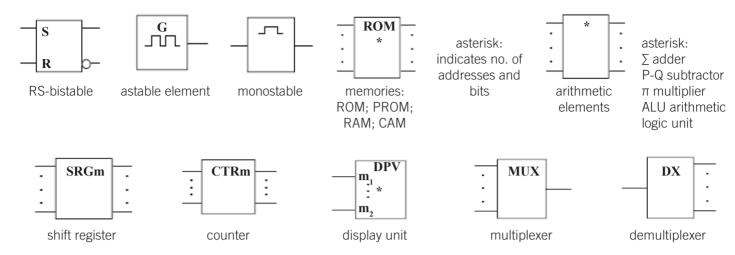


Transistors:

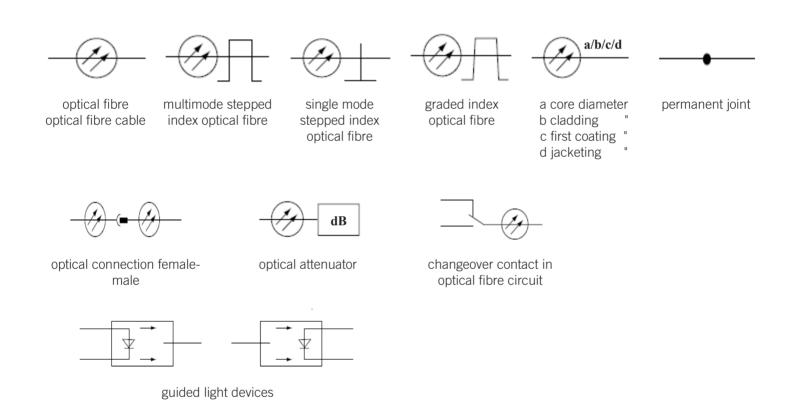




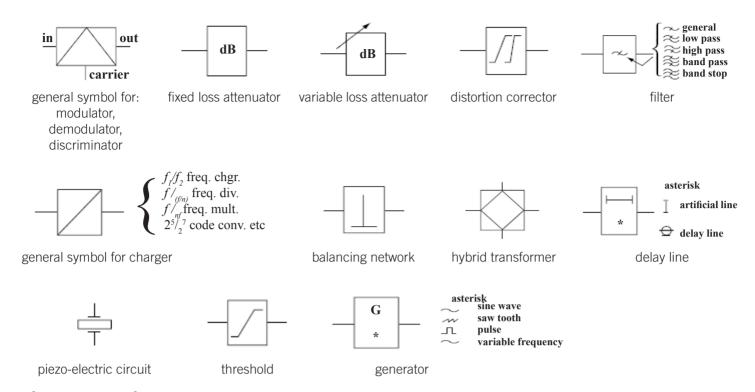
Logic symbols (continued)



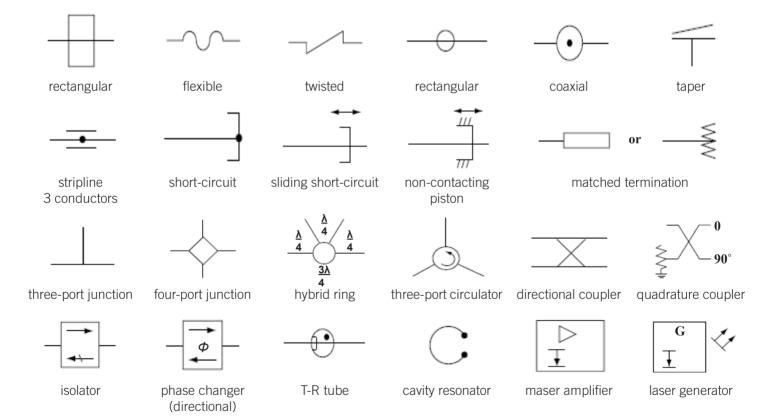
Optic fibre symbols



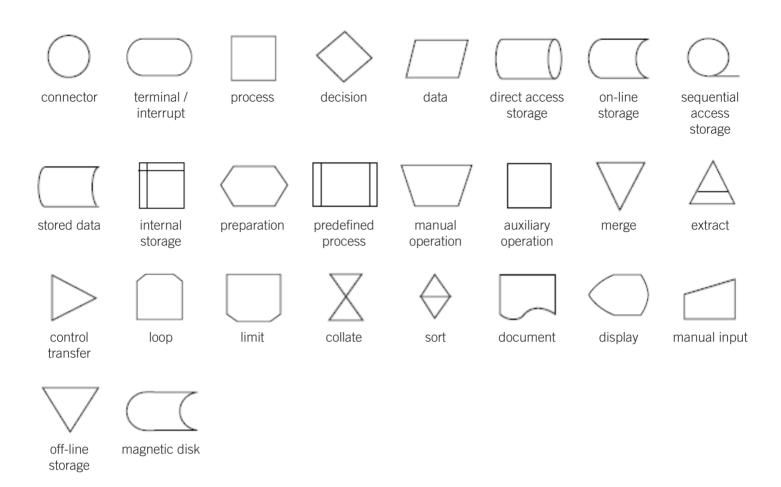
Telecommunication symbols



Microwave devices



Flowchart symbols



13. Some Abbreviations

Commonly used abbreviations in optical, logic and microprocessor circuits

Abbreviation	Description	Abbreviation	Description
100			
ACC	accept	INH	inhibit
ACK	acknowledge	INT	interrupt
ADR	address	1/0	input / output
ALU	arthmetic logic unit		
		LD	load
BCD	binary code decimel	LOG 1	logical one
BCTR	bit counter	LOG Z	logical zero
BIN	binary	LSB	least-significant bit
BPS	bits per second		
BUF	buffer	MAR	memory address register
BUS	bus	мм	main memory
В	byte	MPX	multiplex
	Syle	MR	memory register
CAR	carry	MSB	most significant bit
CC	condition code	MUX	multiplexor
CE	chip enabled		1 .
		μР	microprocessor
CLK	clock		
CLR	clear	N	negation
COMP	compare		
CP	clock pulse	OCT	octal
CR	clock register	0P	operation
CT	count		
CTR	counter	PAR	parity
CY	cycle	PC	program counter
		PE	parity error
D	data	PU	pull up
DEC	decimal		
DEL	delay	RAM	random access memory
DIN	data in	REG	register
DOUT	data out	RES	reset
DR	data out data register	RO	read out
DRAM		ROM	
DRAIN	dynamic random access memory		read only memory
FAL		RUN	run
EN	enable	OFT	1
END	end	SET	set
EPROM	electronic programmable read only memory	SH	shift
ERASE	erase	SRAM	static random access memory
ERR	error	START	start
EXOR	exclusive or	STOP	stop
		STR	storage
F	function	SYNC	synchronisation
FF	flip-flop		
FIF0	first in - first out	TERM	terminate
		TO	to (transfer)
G	gate	TP	time pulse
GEN	generate	TRIG	trigger
GND	ground		
	0.50110	WI	write in
HEX	hexidecimal	WR	write
IILA	Hevidecillai	WIN	I write

Component identification abbreviations

Abbreviation	Description	Abbreviation	Description
AE	aerial	L	inductor
		LK	link
В	battery	LP	lamp
BB	busbar	LS	loudspeaker
С	capacitor	М	motor
СВ	circuit breaker	ME	meter
СК	clock	MG	motor generator
CON	contactor	MIC	microphone
CSR	controlled semicondustor rectifier	MK	morse key
		ML	module
D	diode	MT	telephone handset
		MX	matrix
EQ	equaliser		
		PCC	photoconductive cell
F	fan	PEC	photoelectric cell
FB	ferrite disc or bead	PL	plug
FC	ferrite core		
FL	filter	RE	recording instrument or meter
FS	fuse		
FW	field winding	SD	surge diverter of any type
		SE	sealing end
G	generator	SEM	semaphore indicator
		SHW	shunt winding
Н	heater	SRAM	static random access memory
HC	heat coil	SW	seires winding
HD	hydrophone		
		TD	transductor
IC	integrated circuit	TL	telephone receiver
IREG	induction regulator		
ISL	isolator	U	unit
K	key	VB	vibrator

14. Letter and Digit Code for R & C Values

For resistors, R, K, M, G and T are used as multipliers for 1, 10^3 , 10^6 , 10^9 and 10^{12} , respectively, of resistance values expressed in ohms, whilst for capacitors, p, n, μ , m and F are used as multipliers for 10^{-12} , 10^{-9} , 10^{-6} , 10^{-3} and 1, respectively, of the capacitance values expressed in farads.

For example:

Resistance values	Coded marking	Capacitance values	Coded marking
0.15 Ω	R15	0.15 pF	p15
1.5 Ω	1R5	1.5 pF	1p5
15.0 Ω	15R	15.0 pF	15p
1.5 kΩ	1K5	1.5 nF	1n5
150 kΩ	150K	150 nF	150n
$1.5~{\sf M}\Omega$	1M5	1.5 μF	1μ5
15 ΜΩ	15M	15 μF	15µ
1.5 GΩ	1G5	1.5 mF	1m5
1.5 ΤΩ	1T5	15 mF	15m

Appendix A

List of Standards used in complilation of 'Units & Symbols'

British Standards Institution (BSI) Publications

BS 3363: 1988	Letter symbols for semiconductor devices and integrated microcircuits
BS 3939: 1992	Graphical symbols for electrical power, telecommunications and electronics diagrams
BS 4058: 1995	Data processing flow chart symbols, rules and conventions
BS 5070: 1991	Engineering diagram drawing practice. Part 4: recommendations for logic diagrams
BS 5555: 1993	SI Units and recommendations for the use of their multiples (ISO 1000: 1992) and of certain other units
BS 5775: 1993	Quantities, units and symbols. Part 5: electricity and (ISO 31: 1992) magnetism. Part 11: mathematical
	signs and symbols for use in the physical sciences and technology

Note: The information given in the Booklet is in accordance (where relevant) with the Council* Directive on Units of Measurement (1991).

^{*}The Council of the European Communities

Appendix B

Typefaces used

English Alphabet

Upper case upright	Lower case upright	Upper case sloping	Lower case sloping
A	a	A	a
В	b	$\stackrel{A}{B}$	b
C	c	C	c
D	d	D	d
E	e	E	e
F	f	F	f
G	g	G	g
Н	h h	H	$\overset{\circ}{h}$
Ī	i	I	i
J	i	\overline{J}	i
K	k	K	$\stackrel{\circ}{k}$
L	1	L	l
M	m	M	m
N	n	N	n
O	o	O	o
P	p	P	p
Q	q	Q	\overline{q}
R	r	Q R	r
S	S	S	S
T	t	T	t
U	u	U	u
V	v	V	v
W	w	W	w
X	x	X	x
Y	y	Y	y

Appendix B

Typefaces used

Greek Alphabet

	Upper case upright	Lower case upright	Upper case sloping	Lower case sloping
			,	
alpha	A	α	A	α
beta	В	β	В	β
gamma	Γ	γ	Γ	γ
delta	Δ	δ, δ^*	Δ	δ
epsilon	E	ε	E	ε
zeta	Z	ζ	Z	ζ
eta	H	η	H	η
theta	Θ	θ	Θ	θ
iota	I	ι	I	l
kappa	K	κ	K	κ
lambda	Λ	λ	Λ	λ
mu	M	μ	M	μ
nu	N	ν	N	v
χi	Ξ	ξ	arnething	ξ
omicron	O	0	0	0
pi	П	π	П	π
rho	P	ρ	P	ρ
sigma	Σ	σ	Σ	σ
tau	T	τ	T	τ
upsilon	Y	υ	Y	υ
phi	Φ	φ	Φ	φ
chi	X	χ	X	χ
psi	Ψ	Ψ	Ψ	Ψ
omega	Ω	ω	arOmega	ω

^{*}Used only for partial differential coefficients



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